# Small-volume hyperbolic manifolds constructed from Coxeter groups 

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#### Abstract

Using the symmetric group $S_{n+1}$ and related hyperbolic Coxeter groups [ $3,3, \ldots, 3,6]$, we construct cusped hyperbolic $n$-manifolds of small volume having small rank fundamental group, for $n \leqslant 5$. In particular, we find a cusped orientable arithmetic hyperbolic 5-manifold $M_{*}^{5}$ of volume $13 \zeta(3) / 2$ with $\operatorname{rank}\left(\pi_{1}\left(M_{*}^{5}\right)\right)=3$, starting from the ideal hyperbolic birectified 5 -simplex described in a recent paper by the second author.


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## 1 | INTRODUCTION

The aim of this work is to construct and describe cusped hyperbolic manifolds of small volume with small rank fundamental groups. We are especially interested in the case of $n$-manifolds of dimension $n \leqslant 5$ that are commensurable with an ideal $k$-rectified regular simplex tesselating hyperbolic space $\mathbb{H}^{n}$ (for some $k \geqslant 0$ ). This means that both space forms admit a common finitesheeted cover, or in other words, that the associated discrete groups of hyperbolic isometries are commensurable (in the wide sense).

It is a classical fact that the thrice-punctured sphere $\Sigma_{3}$ is one of minimal volume among all orientable hyperbolic surfaces. One way to construct the surface $\Sigma_{3}$ is to glue together two ideal triangles $S_{\text {reg }}^{\infty}$, each of area $\pi$. Its fundamental group $\pi_{1}\left(\Sigma_{3}\right)$ has rank 2 , is arithmetic, and is commensurable with the hyperbolic Coxeter group $[3, \infty]$ and the modular group $\operatorname{PSL}(2, \mathbb{Z})$.

The Gieseking manifold $G$ is a non-orientable hyperbolic 3-manifold with one cusp, constructible from an ideal (0-rectified) regular tetrahedron $S_{\text {reg }}^{\infty} \subset \mathbb{H}^{3}$ with dihedral angle $\frac{\pi}{3}$, by glueing facets together in pairs. Its fundamental group $\pi_{1}(G)$ has rank 2 and admits the

[^0]presentation $\left\langle u, v \mid u^{2} v^{2}=v u\right\rangle$. Also $\pi_{1}(G)$ is arithmetic and commensurable with the hyperbolic Coxeter group $[3,3,6]$, as well as with the Eisenstein modular group $\operatorname{PSL}(2, \mathbb{Z}[\omega])$, where $\omega=(-1+\sqrt{-3}) / 2$ is a primitive cubic root of unity. In [1], Adams proved that $G$ has minimal volume $\nu_{3}$ among all cusped hyperbolic 3-manifolds, with $\nu_{3}=\operatorname{vol}_{3}\left(S_{\text {reg }}^{\infty}\right)=\frac{3^{5 / 2}}{2 \pi^{2}} \zeta_{\mathbb{Q}(\sqrt{-3})}(2)$, where $\zeta_{K}(s)$ denotes the Dedekind zeta function of the number field $K$.

Due to constructions of Ratcliffe-Tschantz [21, 23] and Kolpakov-Martelli [16], there are many non-isometric orientable and non-orientable cusped hyperbolic 4-manifolds of small volume. These constructions are almost all based on the ideal regular 24 -cell $\mathcal{C}$, whose symmetry group is given by the arithmetic Coxeter group [3,4,3,4]. The latter is commensurable with the pseudomodular group $\operatorname{PSL}(2, \mathbb{Z}[i, j])$ whose coefficients are in the ring of Hamilton integers $\mathbb{Z}[i, j]$; see [10, ch. 15.2]. Although the 1171 examples of Ratcliffe and Tschantz described in [21] are of minimal volume $\nu_{4}=\frac{4 \pi^{2}}{3}$, with five or six cusps, the manifold of volume $4 \nu_{4}$ constructed by Kolpakov and Martelli has only one cusp. Recently, in [23], Ratcliffe and Tschantz showed that there are exactly four hyperbolic 4-manifolds obtained from $C$, with a single cusp and of volume $\nu_{4}$, up to isometry. These four manifolds are all non-orientable.

In [22, Theorem 2], Ratcliffe and Tschantz classified all the orientable hyperbolic 5-manifolds whose fundamental groups are torsion-free subgroups of (minimal possible) index 32 in the congruence two subgroup $\Gamma(2)$ of positive units of the Lorentzian quadratic form $x_{1}^{2}+\cdots+x_{5}^{2}-x_{6}^{2}$. The group $\Gamma(2)$ is a hyperbolic Coxeter group associated with a non-compact right-angled fundamental polyhedron of volume $\frac{7 \zeta(3)}{8}$ having 16 facets. One of these 5 -manifolds has a symmetry group of order 16 that acts freely on the manifold. It turns out that the resulting quotient manifold $N^{5}$ has two cusps and volume $\frac{7 \zeta(3)}{4}$, which is the smallest known volume of a complete hyperbolic 5-manifold; see [22, Section 9].

In this work, we construct cusped hyperbolic $n$-manifolds for $3 \leqslant n \leqslant 5$, by considering ideal $(n-3)$-rectified regular simplices $r_{n-3} \hat{S}_{\text {reg }}$ that give rise to a tessellation of $\mathbb{H}^{n}$. The symmetry group of such an object $r_{n-3} \hat{S}_{\text {reg }} \subset \mathbb{H}^{n}$ is related to the symmetric group $S_{n+1}$ and to the hyperbolic Coxeter groups $\hat{\Gamma}_{n}=[3,3, \ldots, 3,6]$ (or their duals $[6,3, \ldots, 3,3]$ ) of rank $n+1$. Our strategy is to find the smallest index of a torsion-free subgroup in each of these Coxeter groups $\hat{\Gamma}_{n}$, for small $n$, and then to show that the smallest index of a torsion-free subgroup in the Coxeter group [6,3,3,3,3,6] is equal to 2880 .

For $n=3$, the group $\hat{\Gamma}_{3}=[3,3,6]$ is related to the ideal regular tetrahedron $S_{\text {reg }}^{\infty}=r_{0} \hat{S}_{\text {reg }} \subset \mathbb{H}^{3}$, and we rediscover Gieseking's single-cusped manifold $G$ as described earlier.

For $n=4$, we find a torsion-free subgroup $\Gamma_{*}^{4}$ of minimum index 720 in the arithmetic Coxeter pyramid group $\Gamma_{4}=[\infty, 3,3,3,6]$ of covolume $\frac{\pi^{2}}{540}$; see [13]. The related quotient space $M_{*}^{4}=$ $\mathbb{H}^{4} / \Gamma_{*}^{4}$ yields a non-orientable 4-cusped hyperbolic manifold of Euler characteristic $\chi\left(M_{*}^{4}\right)=1$. The group $\Gamma_{4}$ is the finite-covolume counterpart of the group $\hat{\Gamma}_{4}$, and it is incommensurable to the Coxeter simplex group [3,4,3,4]; see [8]. Furthermore, $\Gamma_{4}$ contains as a subgroup of index $5!=120$ the group generated by the reflections in the facets of the ideal 1-rectified Coxeter 5 cell $\mathcal{R}=r_{1} \hat{S}_{\text {reg }} \subset \mathbb{H}^{4}$. The manifold $M_{*}^{4}$ is commensurable to the orientable manifold $N^{4}$ with $\chi\left(N^{4}\right)=1$ constructed by Riolo and Slavich in a different way; see [24, 25].

For $n=5$, we find there is an orientable 2-cusped hyperbolic manifold $M_{*}^{5}$ of small volume and with small rank fundamental group, closely related to the ideal birectified 6-cell $\mathcal{B}=r_{2} \hat{S}_{\text {reg }}$ with dihedral angles $\frac{\pi}{3}$ and $\frac{\pi}{2}$. The polyhedron $\mathcal{B}$ is highly symmetric and can be barycentrically decomposed into $6!=720$ Coxeter pyramids with symbol [6,3,3,3,3,6], with each one having volume $\frac{13 \zeta(3)}{5760}$; see [15].

The fundamental group of the manifold $M_{*}^{5}$ is isomorphic to a torsion-free subgroup of minimal possible index (namely, 2880) in the arithmetic group $\Gamma_{5}=[6,3,3,3,3,6]$. (By the way, $\Gamma_{5}$ also contains a subgroup of infinite index isomorphic to $\hat{\Gamma}_{5}=[6,3,3,3,3]$.) The torsion-free subgroup of index 2880 in $\Gamma_{5}$ was found with the help of the software system MAGMA [2] and methods analogous to those used by the first author in [4]. In particular, the volume of $M_{*}^{5}$ is $\frac{13 \zeta(3)}{2}$, and its symmetry group $I\left(M_{*}^{5}\right)$ has order 24 . Furthermore, the group $\pi_{1}\left(M_{*}^{5}\right)$ has rank 3 , with a presentation in terms of three orientation-preserving isometries, where two are loxodromic elements of equal translation length, and the third is parabolic.

In comparison with the volume $\frac{7 \zeta(3)}{4}$ of the manifold $N^{5}$ found by Ratcliffe and Tschantz [22], the manifold $M_{*}^{5}$ is larger than $N^{5}$. Observe that the fundamental groups of $M_{*}^{5}$ and $N^{5}$, as with the associated Coxeter groups, are incommensurable; see [8]. Now if there were a subgroup $H$ of $I\left(M_{*}^{5}\right)$ of order $|H| \geqslant 4$ acting without fixed points on $M_{*}^{5}$, as in [22], then the quotient manifold $M_{*}^{5} / H$ would have volume strictly less than that of $N^{5}$, but it turns out that there is no such subgroup in $I\left(M_{*}^{5}\right)$.

The rest of this paper is organised as follows. In Section 2, we provide some necessary background about hyperbolic Coxeter groups, Coxeter polyhedra and their description by Coxeter symbols, and for $3 \leqslant n \leqslant 5$, we present the relation between the Coxeter groups $\hat{\Gamma}_{n}=[3, \ldots, 3,6]$, their associated groups $\Gamma_{n}$ of known finite covolume, and ideal ( $n-3$ )-rectified regular simplices in $\Vdash^{n}$. In Section 3, we first prove Theorem 1, concerning the smallest index of a torsion-free subgroup in each of the Coxeter groups $[3,3, \ldots, 3,6]$ of rank 3-6. In the case of [3,3,3,3,6], the smallest index of a torsion-free subgroup is 1440 , and in contrast to this, we then show that the smallest index of a torsion-free subgroup of the Coxeter group [6,3,3,3,3,6] is 2880 . Properties of the corresponding hyperbolic 5-manifold $M_{*}^{5}$ of volume $\frac{13 \zeta(3)}{2}$ are summarised in Theorem 2. In Section 4, we give additional information about the manifold $M_{*}^{5}$ and present our findings about the symmetry group $I\left(M_{*}^{5}\right)$ in Theorem 3. We also include a comparison with the 5-manifold $Q^{5}$ constructed by Felikson and Tumarkin [6] by means of quiver mutations, and in Section 5, we complete the picture, providing constructions of small volume cusped hyperbolic $n$-manifolds for $n=3$ and $n=4$.

## 2 | THE COXETER GROUPS [3, 3, ... 3, 6] AND THE HYPERBOLIC REFLECTION GROUPS $\Gamma_{n}$ OF FINITE COVOLUME

Let $\mathbb{X}^{n}$ denote either the sphere $\mathbb{S}^{n}$, or Euclidean space $\mathbb{E}^{n}$, or hyperbolic space $\mathbb{H}^{n}$, of dimension $n$. We may interpret $\mathbb{X}^{n}$ via its linear model embedded in a quadratic space $Y^{n+1}$, so that

$$
\mathbb{H}^{n}=\left\{x \in \mathbb{R}^{n+1} \mid q_{n}(x)=x_{1}^{2}+x_{2}^{2}+\cdots+x_{n}^{2}-x_{n+1}^{2}=-1, x_{n+1}>0\right\} .
$$

Furthermore, denote by Isom $\mathbb{X}^{n}$ the isometry group of $\mathbb{X}^{n}$. Recall that the group Isom $\mathbb{H}^{n}$ is isomorphic to the group $\mathrm{O}^{+}(n, 1)$ of positive Lorentz matrices (see [19, Chapter 3]), that is,

$$
\begin{equation*}
\mathrm{O}^{+}(n, 1)=\left\{A \in \operatorname{Mat}(n+1, \mathbb{R}) \mid A^{t} J A=J,[A]_{n+1, n+1}>0\right\}, \tag{2.1}
\end{equation*}
$$

where $J=\operatorname{diag}(1,1, \ldots, 1,-1)$ is the diagonal matrix associated with $q_{n}$.
For a given subgroup $\Gamma$ of Isom $\mathbb{H}^{n}$, the quotient space $\mathbb{H}^{n} / \Gamma$ is a (complete) hyperbolic $n$ orbifold if $\Gamma$ is discrete. In addition, if the group $\Gamma$ has no torsion elements (i.e., no non-trivial elements of finite order), then $\mathbb{H}^{n} / \Gamma$ is a hyperbolic $n$-manifold, which we will denote by $M$.

In this paper, we consider only finite volume quotients $V$ of $\mathbb{M}^{n}$ by discrete groups $\Gamma$ of hyperbolic isometries (see [3, 19]). Accordingly, the group $\Gamma$ is finitely generated, and the volume of $V$ can be identified with the volume of a (closed) fundamental domain for the deck group $\pi_{1}(V)$ of $V$, which is isomorphic to $\Gamma$. By Selberg's lemma [19, Chapter 7], the group $\Gamma$ has a torsion-free (normal) subgroup of finite index, so the space $V$ is finitely covered by a hyperbolic manifold. Finally, recall from [20] that the isometry group $I(V)$ of a finite volume orbifold $V=\mathbb{H}^{n} / \Gamma$ is a finite group isomorphic to the quotient group $N(\Gamma) / \Gamma$, where $N(\Gamma)$ is the normaliser of $\Gamma$ in Isom $\mathbb{H}^{n}$.

Two groups in Isom $\mathbb{H}^{n}$ are commensurable in the wide sense (or commensurable, for short) if the intersection of one group with some conjugate of the other group is of finite index in both groups. Commensurability is an equivalence relation, which preserves properties such as cocompactness, finite covolume, and arithmeticity.

A geometric Coxeter group is a discrete subgroup $\Gamma$ of Isom $\mathbb{X}^{n}$ generated by a finite set $S$ of reflections $s_{i}$ in hyperplanes $H_{i}$ of $\mathbb{X}^{n}$, for $1 \leqslant i \leqslant|S|$. The cardinality $|S|$ of $S$ is called the rank of $\Gamma$. The generators in $S$ satisfy the relations $s_{i}^{2}=1$ and $\left(s_{i} s_{j}\right)^{m_{i j}}=1$ where $m_{i j}=m_{j i} \in\{2,3, \ldots, \infty\}$ for all $i, j$. Here, $m_{i j}=\infty$ means that $s_{i} s_{j}$ does not have specified finite order. Associated with $\Gamma$ is the Coxeter diagram $\Sigma=\Sigma(\Gamma)$, which is a graph with nodes $v_{i}$ (corresponding to $s_{i}$ and $H_{i}$ ), with $v_{i}$ and $v_{j}$ joined by an edge with label $m_{i j}$ whenever $m_{i j} \geqslant 3$. (This label is usually omitted when $m_{i j}=3$.) Observe that in the hyperbolic case, if $H_{i}$ and $H_{j}$ are parallel and intersect on $\partial \mathbb{H}^{n}$ (or lie at hyperbolic distance $l>0$ from each other), then the nodes $\nu_{i}$ and $\nu_{j}$ are connected by an edge with label $\infty$ (or by a dotted edge with label $l$ ). Hence the Coxeter diagram $\Sigma$ of $\Gamma$ depicts the intersection behaviour of the hyperplanes $H_{i}=v_{i}^{\perp}$ (for $1 \leqslant i \leqslant|S|$ ) and the facets of the associated Coxeter polyhedron $P=\cap_{1 \leqslant i \leqslant|S|} H_{i}^{-} \subset \mathbb{X}^{n}$, where the closed half spaces $H_{i}^{-}$are oriented by means of the unit vectors $v_{i}$ orthogonal to $H_{i}$, pointing outwards with respect to $P$. The polyhedron $P$ is the closure of a fundamental domain of $\Gamma$, and the group $\Gamma$ is said to be offinite covolume if $P$ has finite volume.

We use a Coxeter symbol to depict a Coxeter diagram of simple combinatorial type. As explained in [11, Appendix], for example, this symbol can take the form $\left[p_{1}, p_{2}, \ldots, p_{k}\right]$ or $\left[q_{1}, q_{2}, \ldots, q_{l}, \infty\right.$ ] with integer labels $p_{i}, q_{j} \geqslant 3$, for a linear Coxeter diagram with $k+1$ or $l+2$ nodes and with edges marked by the respective weights. In a similar way, the Coxeter symbol [ $\infty, q_{1}, q_{2}, \infty$ ] with integers $q_{1}, q_{2} \geqslant 3$ denotes a linear Coxeter diagram with five nodes.

The spherical and Euclidean Coxeter groups were classified by Coxeter [5] in 1934. The list of irreducible spherical Coxeter groups is comparatively short. In this paper, the group $\mathcal{A}_{n}=$ $[3,3, \ldots, 3]$ of order $(n+1)$ ! is of particular interest as it is isomorphic to the symmetric group $S_{n+1}$, under an isomorphism that takes its generator $s_{i}$ to the single transposition $(i, i+1)$, for $1 \leqslant i \leqslant n$. Alternatively, it can be viewed as the symmetry group of a regular simplex $S_{\text {reg }} \subset \mathbb{S}^{n-1}$, with each $s_{i}$ interpreted as a reflection in $\mathbb{R}^{n}$.

For hyperbolic Coxeter groups of finite covolume, Vinberg [26] developed a highly satisfactory theory allowing one to analyse their arithmetic nature and the combinatorial-metrical structure of their Coxeter polyhedra $P$ in terms of the Gram matrix $G=G(P)$. For example, a finitecovolume hyperbolic Coxeter group with non-compact polyhedron $P$ is arithmetic (and defined over $\mathbb{Q}$ ) if and only if all coefficient cycles (related to closed paths on the Coxeter diagram) of $2 \cdot G$ are rational integers. Despite this insight, Coxeter groups of finite covolume in Isom $\mathbb{H}^{n}$ are classified only for very small rank $|S| \geqslant n+1$. For an up-to-date list and non-existence bounds, see [7].

Here we focus on finite-covolume hyperbolic Coxeter groups $\Gamma_{n}$ given by linear diagrams, with associated non-compact Coxeter polyhedron $P \subset \mathbb{H}^{n}$, such that $\Gamma_{n}$ has minimal rank and contains $\mathcal{A}_{n}=[3,3, \ldots, 3]$ as a subgroup.


FIGURE 1 The Coxeter group $\Gamma_{2}=[3, \infty]$


FIGURE 2 The Coxeter group $\Gamma_{3}=\hat{\Gamma}_{3}=[3,3,6]$

For example, when $n=2$, there is the arithmetic Coxeter group $\Gamma_{2}=[3, \infty]$ of rank 3 given in Figure 1, with rotation subgroup $\Gamma_{2}^{+}$isomorphic to the rational modular group $\operatorname{PSL}(2, \mathbb{Z})$. The group $\Gamma_{2}$ generates the symmetry group of an ideal triangle $S_{\text {reg }}^{\infty} \subset \mathbb{H}^{2}$ of area $\pi$.

In geometric terms, by decomposing the triangle $S_{\text {reg }}^{\infty}$ barycentrically into 3! isometric copies of the right-angled triangle $R_{2}=\Delta\left(0, \frac{\pi}{3}, \frac{\pi}{2}\right)$ with angle $\frac{\pi}{3}$ and one vertex on the boundary at infinity of $\mathbb{H}^{2}$, the generators of the group $\Gamma_{2}$ are the reflections in the geodesic lines bounding $R_{2}$.

For $n=3$, the group $\Gamma_{3}$ of rank 4 has a diagram given in Figure 2 and coincides with the group $\hat{\Gamma}_{3}=[3,3,6]$. It is of arithmetic nature, and the commutator subgroup of $\Gamma_{3}$ is isomorphic to the Eisenstein modular group $\operatorname{PSL}(2, \mathbb{Z}[\omega])$ where $\omega=(-1+\sqrt{-3}) / 2$; see [10, Section 14.3]. The group $\Gamma_{3}$ is generated by the reflections $a, b, c, d$ in the facets of a non-compact Coxeter tetrahedron $R_{3}$, with precisely one vertex on the boundary at infinity, given by $A=H_{b} \cap H_{c} \cap H_{d}$. The stabiliser of $A$ in $\Gamma_{3}$ is the Euclidean Coxeter subgroup with symbol [3,6]. The covolume of $\Gamma_{3}$ can be computed in two different ways. Classically, the geometrical approach due to Lobachevsky yields

$$
\operatorname{vol}_{3}\left(R_{3}\right)=\frac{1}{8} \mathrm{~J}\left(\frac{\pi}{3}\right) \approx 0.04228
$$

where $\mathrm{J}(\omega)=-\int_{0}^{\omega} \log |2 \sin t| \mathrm{d} t$ denotes the Lobachevsky function; see [12], for example.
The tetrahedron $R_{3}$ is the characteristic simplex of an ideal regular tetrahedron $S_{\text {reg }}^{\infty}$ with dihedral angle $\frac{\pi}{3}$ and with centre $D=H_{a} \cap H_{b} \cap H_{c}$. By barycentric decomposition, the Coxeter simplex $S_{\text {reg }}^{\infty}$ can be cut into $4!=24$ isometric copies of $R_{3}$, so that $\operatorname{vol}_{3}\left(S_{\text {reg }}^{\infty}\right)=3 \mathrm{~J}\left(\frac{\pi}{3}\right)$. Notice that the group $\Gamma_{3}$ is commensurable with the Coxeter pyramid group $\Gamma_{3}^{\prime}=[\infty, 3,6, \infty]$ in Isom $\mathbb{H}^{3}$, which implies that their quotient spaces $\mathbb{H}^{3} / \Gamma_{3}$ and $\mathbb{H}^{3} / \Gamma_{3}^{\prime}$ are covered by a common manifold; see [8]. The Coxeter pyramid $[\infty, 3,6, \infty]$ can be decomposed into the tetrahedra $[3,6,3]$ and $[6,3,6]$ so that its volume equals $\frac{5}{4} \mathrm{~J}\left(\frac{\pi}{3}\right)$; see [12]. In contrast with $\Gamma_{3}^{\prime}$, the Coxeter pyramid group $\Theta=[\infty, 3,3, \infty$ ] is not commensurable with $\Gamma_{3}$ and $\Gamma_{3}^{\prime}$. (It contains $\mathcal{A}_{3}$ as well, but as such its rank is not minimal.)

For $n=4$, there are no non-compact Coxeter simplices of finite volume with linear diagram containing the diagram for $\mathcal{A}_{4}$ as a subgraph; see [27, Part II, Chapter 5]. There is, however, an infinite volume Coxeter polyhedron $\hat{R}_{4} \subset \mathbb{H}^{4}$ with symbol [3,3,3,6], giving rise to the reflection group $\hat{\Gamma}_{4}$ of rank 5 . By taking into account the exterior of hyperbolic space and by passing to the projective ball model $K^{4}$ for $\mathbb{H}^{4}$ in $\mathbb{R} P^{4}$, the polyhedron $\hat{R}_{4}$ can be interpreted as the characteristic simplex of a regular simplex $\hat{S}_{\text {reg }}$ with dihedral angle $\frac{\pi}{3}$, all of whose edges lie outside of $\mathbb{H}^{4}$ but are tangent at their midpoints to $\partial \mathbb{H}^{4}$. By taking the (hyperbolic) convex hull of all these edge midpoints of $\hat{S}_{\text {reg }}$, one obtains an ideal hyperbolic 4-polyhedron $\mathcal{R}$ with dihedral angles $\frac{\pi}{3}$ and $\frac{\pi}{2}$ whose symmetry group is isomorphic to a subgroup of $S_{5}$. More precisely, this process is given by polar truncation of each of the ultra-ideal vertices of $\hat{S}_{\text {reg }}$ and is called (simple) rectification of $\hat{S}_{\text {reg }}$,


FIGURE 3 The Coxeter group $\Gamma_{4}=[\infty, 3,3,3,6]$


FIGURE 4 The group $\Gamma_{5}=[6,3,3,3,3,6]$
indicated by $r_{1} \hat{S}_{\text {reg }}=\mathcal{R}$; see [15, Section 3.2], [25]. This process also gives rise to a (truncated) finite volume Coxeter polyhedron $R_{4} \subset \mathbb{H}^{4}$ with symbol [ $\infty, 3,3,3,6$ ], with precisely one ideal vertex, and which barycentrically decomposes $\mathcal{R}$ into $5!=120$ isometric copies. The Coxeter diagram of $R_{4}$ and the associated reflection group $\Gamma_{4}$ are depicted in Figure 3.

Next, by [13, Appendix], as the volume of the polyhedron $R_{4}$ is $\frac{\pi^{2}}{540}$, the volume of the ideal rectified regular simplex $r_{1} \hat{S}_{\text {reg }}=\mathcal{R} \subset \mathbb{M}^{4}$ is given by

$$
\begin{equation*}
\operatorname{vol}_{4}(\mathcal{R})=5!\operatorname{vol}_{4}([\infty, 3,3,3,6])=\frac{2 \pi^{2}}{9} . \tag{2.2}
\end{equation*}
$$

Observe that the Coxeter group $\Gamma_{4}$ is not commensurable with the Coxeter group [3,4,3,4]. The Coxeter simplex $[3,4,3,4]$ has volume $\frac{\pi^{2}}{864}$ and takes part (as characteristic simplex) in the barycentric decomposition of the ideal right-angled 24 -cell $\mathcal{C} \subset \mathbb{1}^{4}$ into 1152 isometric copies (see [8]). In particular, the volume of $\mathcal{C}$ is $\frac{4 \pi^{2}}{3}$. Both groups $\Gamma_{4}$ and $[3,4,3,4]$ are arithmetic and closely related to certain pseudo-modular groups of quaternionic Clifford matrices as described in [10, Section 15.2].

For $n=5$, as in the case $n=4$, there are no finite-covolume hyperbolic Coxeter groups of rank 6 with linear diagram containing the diagram for $\mathcal{A}_{5}$ as a subgraph, but there is an infinite volume Coxeter polyhedron $\hat{R}_{5} \subset \mathbb{H}^{5}$ with symbol [3,3,3,3,6], which belongs to the ideal birectified regular 5 -simplex $r_{2} \hat{S}_{\text {reg }}=: \mathcal{B}$ with dihedral angles $\frac{\pi}{3}$ and $\frac{\pi}{2}$. More concretely, by passing to the projective ball model $K^{5}$ for $\mathbb{H}^{5}$, the polyhedron $\hat{R}_{5}$ can be associated with the characteristic simplex of a regular simplex $\hat{S}_{\text {reg }}$ in the ambient space of $K^{5}$, with all of its 2-dimensional faces lying outside but tangent at their centres to the boundary sphere at infinity $\partial K^{n}$. The truncation of the ultraideal vertices $v_{i}$ of $\hat{S}_{\text {reg }}$ by means of their polar hyperplanes $\pi_{i}$ (for $1 \leqslant i \leqslant 6$ ) has the property that $\Varangle\left(\pi_{i}, \pi_{k}\right)=\frac{\pi}{3}$ whenever $i \neq k$. This process yields a finite-volume hyperbolic Coxeter polyhedron with dihedral angles $\frac{\pi}{3}$ and $\frac{\pi}{2}$, coinciding with the (hyperbolic) convex hull of all ideal centres of the 2 -faces of $\hat{S}_{\text {reg }}$, the ideal birectified regular simplex $\mathcal{B}$, whose symmetry group is isomorphic to a subgroup of $S_{6}$. For more details, see [15, Section 3.2].

The truncation of $\hat{S}_{\text {reg }}$ induces a truncation of $\hat{R}_{5}$ and provides a finite volume Coxeter polyhedron $R_{5} \subset \mathbb{H}^{5}$, with precisely one vertex on $\partial \mathbb{H}^{5}$. The associated reflection group $\Gamma_{5}$ has the generators $a, b, c, d, e, f, g$ according to Figure 4 , where the mirror $H_{a}$ associated with $a$ coincides with a truncation hyperplane of $\hat{S}_{\text {reg }}$.

The combinatorial type of $R_{5}$ is that of a pyramid over a product of two triangles whose apex $D$ is the ideal point given by the intersection of the hyperplanes $H_{a}, H_{b}, H_{c}$ and $H_{e}, H_{f}, H_{g}$ of $R_{5}$. More precisely, the Euclidean vertex figure of $D$ is of type [6,3] $\times[3,6]$. In [8], all such Coxeter pyramid groups were classified up to commensurability, and further, it was shown that the group


FIGURE 5 The subgroup $\Lambda_{5}$ of index 4 in $\Gamma_{5}$
$\Gamma_{5}$ does not belong to the commensurability class of the Coxeter simplex group [3,4,3,3,3]. Also it is known by [9] that the quotient space of $\mathbb{H}^{5}$ by the (arithmetic) discrete reflection group [3,4,3,3,3] has minimal volume among all cusped hyperbolic 5-orbifolds. This minimal value has previously been computed in [14] and is given by

$$
\begin{equation*}
\operatorname{covol}_{5}([3,4,3,3,3])=\frac{7 \zeta(3)}{46080} . \tag{2.3}
\end{equation*}
$$

The group $\Gamma_{5}$ contains, as a (normal) subgroup of index 4, the Coxeter pyramid group $\Lambda_{5}$ given by Figure 5. This follows easily by reflecting the Coxeter pyramid given by Figure 4 in the mirror $H_{a}$ and then in $H_{g}$. In other words, the group $\Lambda_{5}$ is generated by the elements $a b a, b, c, d, e, f, g f g$ of $\Gamma_{5}$, and it will play a role in Section 4.

Furthermore, $\Gamma_{5}$ is arithmetic and closely related to the so-called hybrid quaternionic modular group $\mathrm{PS}_{\Delta} \mathrm{L}(2, \mathbb{Z}[\omega, j])$ where $\Delta$ is the Dieudonné determinant of a quaternionic matrix and $\omega=(-1+\sqrt{-3}) / 2$ as usual; see [10, Section 15.5]. The covolume of the group $\Gamma_{5}$ is much harder to compute than the covolume of [3,4,3,3,3] and its commensurable groups. In [15], using the proof of [15, Theorem 2] and relations in the crystallographic Napier cycles defined by the group $\Gamma_{5}$, the second author was able to compute the covolume of $\Gamma_{5}=[6,3,3,3,3,6]$ and that of $\mathrm{PS}_{\Delta} \mathrm{L}(2, \mathbb{Z}[\omega, j])$. Indeed

$$
\begin{equation*}
\operatorname{covol}_{5}([6,3,3,3,3,6])=\frac{13}{5760} \zeta(3) . \tag{2.4}
\end{equation*}
$$

As a consequence, the volume of the ideal birectified regular 5 -simplex $\mathcal{B}$ is 6 !. $\operatorname{covol}_{5}([6,3,3,3,3,6])=\frac{13 \zeta(3)}{8}$.

In Figures 6 and 7, we list the different hyperbolic Coxeter groups as described earlier.

## 3 | TORSION-FREE SUBGROUPS OF SMALL INDEX IN CERTAIN COXETER GROUPS

In this section, we find the smallest index of a torsion-free subgroup in each of the Coxeter groups $[6,3,3, \ldots, 3]$ (and equivalently, in their duals $[3,3, \ldots, 3,6]$ ) of ranks 3 to 6 and explain why the smallest index of a torsion-free subgroup in the [6,3,3,3,3,6] Coxeter group $\Gamma_{5}$ is 2880 .

To do this, we start by noting that $\Gamma_{5}$ is canonically generated by seven reflections $a, b, c, d, e, f, g$, which satisfy the defining relations that can be read off the Coxeter diagram given in Figure 4. We need to know the representatives of conjugacy classes of torsion elements in this group, and we can find those in a similar way to the approach taken in [4] for finding a small index torsion-free subgroup in the [5,3,3,3] Coxeter group.

Specifically, we observe that the group $\Gamma_{5}$ has a natural action as a reflection group in 5 dimensional hyperbolic space $\mathbb{H}^{5}$, and hence that every torsion element is conjugate to a torsion element of one or more of the subgroups generated after removing an element from the

| Coxeter group | Related group in Isom $\mathbb{H}^{n}$ | $\operatorname{covol}_{n}$ |
| :--- | :---: | :---: |
| $[3] \quad$ (spherical) | $\Gamma_{2}=[3, \infty]$ | $\frac{\pi}{6}$ |
| $[3,6]$ (Euclidean) | $\Gamma_{3}^{\prime}=[\infty, 3,6, \infty]$ | $\frac{5}{4} \mathrm{~J}\left(\frac{\pi}{3}\right)$ |

FIGURE 6 The hyperbolic Coxeter groups $\Gamma_{2}$ and $\Gamma_{3}^{\prime}$

| $n$ | $\hat{\Gamma}_{n}$ | $\Gamma_{n}$ | $\operatorname{covol}_{n}$ |
| :---: | :---: | :---: | :---: |
| 3 | $[3,3,6]$ | $[3,3,6]$ | $\frac{1}{8} \mathrm{~J}\left(\frac{\pi}{3}\right)$ |
| 4 | $[3,3,3,6]$ | $[\infty, 3,3,3,6]$ | $\frac{\pi^{2}}{540}$ |
| 5 | $[3,3,3,3,6]$ | $[6,3,3,3,3,6]$ | $\frac{13}{5760} \zeta(3)$ |

FIGURE 7 The hyperbolic Coxeter groups $\hat{\Gamma}_{n}$ and $\Gamma_{n}$
canonical generating set for $\Gamma_{5}$. In the case of [5,3,3,3], every such subgroup was finite, but in this case, it does not happen. Actually, it never happens, because each of the Coxeter groups [6,3,3,3,3], [ $6,3,3,3],[6,3,3]$ and $[6,3]$ and their duals (obtained by reversing the Coxeter diagram) is infinite. Nevertheless, we can make the analogous observation about torsion elements in each of these Coxeter groups, using their actions on 5-, 4- and 3-dimensional hyperbolic space and 2-dimensional Euclidean space, respectively.

For example, the elements $a, b$ and $c$ generate an infinite subgroup isomorphic to the $[6,3]$ Coxeter group, otherwise known as the $(2,3,6)$ triangle group, and each of its torsion elements is conjugate to a torsion element of one or more of the finite subgroups $\langle a, b\rangle \cong D_{6}$ (of order 12), $\langle a, c\rangle \cong C_{2} \times C_{2}$ (of order 4) and $\langle b, c\rangle \cong D_{3}$ (of order 6), and hence to one or more of the elements $a, b, a b,(a b)^{2},(a b)^{3}, c, a c$ and $b c$. (In fact we can drop $b$ or $c$ from this list, as each of them is conjugate to the other in $\langle b, c\rangle \cong D_{3}$.)

Next, $a, b, c$ and $d$ generate a subgroup isomorphic to the $[6,3,3]$ Coxeter group, and each of its torsion elements is conjugate to a torsion element of one or more of either $\langle a, b, c\rangle \cong[6,3]$ or $\langle a, b, d\rangle \cong D_{6} \times C_{2}$ (of order 24) or $\langle a, c, d\rangle \cong C_{2} \times D_{3}$ (of order 12) or $\langle b, c, d\rangle \cong[3,3] \cong S_{4}$ (of order 24).

In this way, we can build a set of representatives of conjugacy classes of torsion elements of each of the seven subgroups generated after removing an element from the given generating set $S=\{a, b, c, d, e, f, g\}$ for $\Gamma_{5}$. This, however, produces a very long list (which interested readers could take some time to find for themselves).

A much better approach is to take the maximally finite subgroups of $\Gamma_{5}$ generated by subsets of $S$, as given in Figure 8.

Now every torsion-free subgroup $H$ of $\Gamma_{5}$ intersects each of these nine subgroups trivially, and so in the natural permutation representation of $\Gamma_{5}$ on (right) cosets of $H$ (by right multiplication), each of these nine subgroups acts fixed-point-freely (i.e., with no non-trivial element fixing a point), and hence with orbits all having the same length as the order of the subgroup. It follows that the index of $H$ in $\Gamma_{5}$ is divisible by the order of each one, and so must be divisible by $\operatorname{LCM}(288,144,240,96,720)=32 \cdot 9 \cdot 5=1440$.

$$
\begin{aligned}
& \langle a, b, d, e, f\rangle \cong\langle a, b\rangle \times\langle d, e, f\rangle \cong D_{6} \times S_{4} \quad \text { (of order 288), } \\
& \langle a, b, d, e, g\rangle \cong\langle a, b\rangle \times\langle d, e\rangle \times\langle g\rangle \cong D_{6} \times D_{3} \times C_{2} \quad \text { (of order 144), } \\
& \langle a, b, d, f, g\rangle \cong\langle a, b\rangle \times\langle d\rangle \times\langle f, g\rangle \cong D_{6} \times C_{2} \times D_{6} \quad \text { (of order 288), } \\
& \langle a, c, d, e, f\rangle \cong\langle a\rangle \times\langle c, d, e, f\rangle \cong C_{2} \times S_{5} \quad \text { (of order 240), } \\
& \langle a, c, d, e, g\rangle \cong\langle a\rangle \times\langle c, d, e\rangle \times\langle g\rangle \cong C_{2} \times S_{4} \times C_{2} \quad \text { (of order 96), } \\
& \langle a, c, d, f, g\rangle \cong\langle a\rangle \times\langle c, d\rangle \times\langle f, g\rangle \cong C_{2} \times D_{3} \times D_{6} \quad \text { (of order 144), } \\
& \langle b, c, d, e, f\rangle \cong S_{6} \quad(\text { of order } 720), \\
& \langle b, c, d, e, g\rangle \cong\langle b, c, d, e\rangle \times\langle g\rangle \cong S_{5} \times C_{2} \quad \text { (of order 240), } \\
& \langle b, c, d, f, g\rangle \cong\langle b, c, d\rangle \times\langle f, g\rangle \cong S_{4} \times D_{6} \quad \text { (of order 288), }
\end{aligned}
$$

FIGURE 8 Maximally finite subgroups of the [6,3,3,3,3,6] Coxeter group $\Gamma_{5}$ obtained after deleting generators

The same arguments as before show that the index of every torsion-free subgroup of one of the Coxeter groups [6,3], [6,3,3], [6,3,3,3] and [6,3,3,3,3] is divisible by $12,24,720$ and 1440 , respectively. Moreover, we can easily use this information to prove the following.

Theorem 1. The smallest index of a torsion-free subgroup in one of the Coxeter groups [6,3], [6,3,3], [6,3,3,3] and [6,3,3,3,3] is 12, 24, 720 and 1440, respectively.

Proof. Let $\{a, b, c\},\{a, b, c, d\},\{a, b, c, d, e\}$ or $\{a, b, c, d, e, f\}$ be the canonical generating set for the relevant Coxeter group, of rank $3,4,5$ or 6 , respectively. Then computations using MAGMA reveal the following:
(1) The subgroup generated by $\{a b a c b, b a b a b c\}$ has index 12 in the [6,3] Coxeter group, intersects each of the subgroups $\langle a, b\rangle,\langle a, c\rangle$ and $\langle b, c\rangle$ trivially (because each of those maximally finite subgroups acts fixed-point-freely on the corresponding coset space) and hence is torsion-free.
(2) The subgroup generated by $\{a b c, b a b c d\}$ has index 24 in the [6,3,3] Coxeter group, intersects each of the subgroups $\langle a, b, d\rangle,\langle a, c, d\rangle$ and $\langle b, c, d\rangle$ trivially (because each of those maximally finite subgroups acts fixed-point-freely on the coset space) and hence is torsion-free.
(3) The subgroup generated by \{abc, babcd, bedcbababcbababcdeca\} has index 720 in the [6,3,3,3] Coxeter group, intersects each of the subgroups $\langle a, b, d, e\rangle,\langle a, c, d, e\rangle$ and $\langle b, c, d, e\rangle$ trivially (because each of those maximally finite subgroups acts fixed-point-freely on the coset space) and hence is torsion-free.
(4) The subgroup generated by \{abcdcbfedcbababa,adcbaedcfedbcaba,abcbd $e d c b f a b c d e c d a b a\}$ has index 1440 in the [6,3,3,3,3] Coxeter group, intersects each of the subgroups $\langle a, b, d, e, f\rangle,\langle a, c, d, e, f\rangle$ and $\langle b, c, d, e, f\rangle$ trivially (because each of those maximally finite subgroups acts fixed-point-freely on the coset space) and hence is torsionfree.

In each of these four cases, the index is equal to the lower bound on it obtained earlier and hence is the minimum index.

In contrast, however, we were unable to find a torsion-free subgroup of the anticipated minimum possible index 1440 in the [6,3,3,3,3,6] Coxeter group $\Gamma_{5}$. We did find one of index 2880, again with the help of MAGMA, namely the subgroup generated by bacbdefdea, cbabedgf geda
and cbabfegf gefdea. In the natural permutation representation of $\Gamma_{5}$ on (right) cosets of this subgroup, each of the nine maximally finite subgroups of $\Gamma_{5}$ in Figure 8 acts fixed-point-freely on the coset space, so the given subgroup contains no torsion element. The abelianisation of this subgroup is $\mathbb{Z}_{7}^{3}$, obtainable using the AbelianQuotientInvariants function in MAGMA.
(In fact, up to conjugacy this subgroup was the only torsion-free subgroup of index 2880 in $\Gamma_{5}$ that we could find, using a range of approaches (including searching for subgroups of index $\frac{2880}{k}$ in subgroups of index $k$ for mid-range divisors $k$ of 2880, and intersections of subgroups of small index, and pre-images of subgroups of appropriate orders in small quotients). It is plausible that the subgroup we found is the only torsion-free subgroup of index 2880 in $\Gamma_{5}$ up to conjugacy, but we could not prove this.)

The quotient $M_{*}^{5}$ of $\mathbb{H}^{5}$ by this subgroup is a manifold with two cusps. Indeed, the Coxeter polyhedron associated with the group $\Gamma_{5}$ has precisely one ideal vertex $v_{0}$, with stabiliser subgroup $\Gamma_{5}\left(v_{0}\right)=\langle a, b, c\rangle \times\langle e, f, g\rangle$. The cusps of this manifold are in one-to-one correspondence with the orbits of the group $\Gamma_{5}\left(v_{0}\right)$ in the action of $\Gamma_{5}$ on the 2880 cosets of the torsion-free subgroup, and an easy MAGMA computation shows that there are two such orbits, of lengths 576 and 2304.

This left us with the somewhat challenging task of showing that there is no torsion-free subgroup of index 1440 . We explain in the following how we did that.

Suppose there is one, say $H$, and again consider the natural permutation representation of $\Gamma_{5}$ on the (right) coset space $\Omega=\left(\Gamma_{5}: H\right)$. In this representation, every finite subgroup of $\Gamma_{5}$ acts fixed-point-freely on $\Omega$, and in particular, the subgroup $J=\langle b, c, d, e, f\rangle$ induces two (regular) orbits of length $\left|S_{6}\right|=720$. These two sub-orbits are linked together by the permutation induced by $a$ to give a transitive permutation representation of $\langle a, b, c, d, e, f\rangle$ satisfying the 'fixed-point-free orbits' test from item (4) in the proof of Theorem 1 and are also linked together by the permutation induced by $g$ to give a transitive permutation representation of $\langle b, c, d, e, f, g\rangle$ satisfying its 'dual' (under the automorphism of $\Gamma_{5}$ that reverses its Coxeter diagram).

We used this information to proceed as follows:
Step 1: We found all transitive permutation representations of the [6,3,3,3,3] Coxeter group of degree 1440 in which the maximal finite subgroups act fixed-point freely, as in the proof of Theorem 1, by determining all ways in which two regular representations of the [3,3,3,3] Coxeter group $S_{6}$ can be linked together in the appropriate way. This took several days of computing time using MAGMA, even after breaking it up into 945 independent sub-cases, depending on how the orbits of the $[3,3,3,3]$ Coxeter subgroup of order 120 generated by $\{c, d, e, f\}$ are linked together by the permutation induced by the generator $a$ (which commutes with each of $c, d, e, f$ ). It produced 19704 transitive representations of degree 1440.

Step 2: We recognised that the representations in Step 1 give all transitive permutation representations of the [3,3,3,3,6] Coxeter group with the analogous property, simply by applying the restriction to $\langle a, b, c, d, e, f\rangle$ of the automorphism $\theta$ of $\Gamma_{5}$ that reverses the order of its generating set, taking ( $a, b, c, d, e, f$ ) to ( $g, f, e, d, c, b$ ).

Step 3: We considered all pairs of the representations found in Steps 1 and 2, to first test if the permutations induced respectively by $a$ and $g$ commute, in which case they give a transitive permutation representation of the [6,3,3,3,3,6] Coxeter group $\Gamma_{5}$, and then (if that test succeeded) to check that the resulting permutation representation gives a fixed-point-free representation of each of the maximally finite subgroups of $\Gamma_{5}$ in the list in Figure 8 . This was straightforward, and required looking only at the orbits of the groups induced by the second, third, fifth and sixth of the finite subgroups listed in Figure 8 (namely the ones containing both $a$ and $g$ ), but also took some considerable time, because of the sheer number of representations coming out of Steps 1 and 2.

Sadly, in Step 3 we found no way of combining pairs from Steps 1 and 2 to give a representation of $\Gamma_{5}$ of the anticipated kind. As it happened, 3120 of the pairs produced permutation representations in which the permutations induced by $a$ and $g$ commute, but all of them failed the fixed-point-free orbits test.

In summary, the previous arguments and computations prove the following.
Theorem 2. The smallest index of a torsion-free subgroup in the Coxeter group [6,3,3,3,3,6] is 2880, achieved, for example, by the torsion-free subgroup generated by bacbdef dea, cbabed gf geda, and cbabfegf gefdea., This subgroup gives rise to a hyperbolic 5-manifold of volume $2880 \cdot \frac{13 \zeta(3)}{5760}=$ $\frac{13 \zeta(3)}{2}$, with two cusps and with first homology group $\mathbb{Z}_{7}^{3}$.

## 4 | THE MANIFOLD $M_{*}^{5}$ AND ITS FUNDAMENTAL GROUP

Here we take a closer look at the manifold described in Theorem 2. The elements,

$$
u:=\text { bacbdefdea }, \quad v:=\text { cbabedgf geda and } w:=\text { cbabfegf gefdea, }
$$

in the Coxeter group $\Gamma_{5}=[6,3,3,3,3,6]$ generate a torsion-free subgroup $\Gamma_{5}^{*}$ of index 2880 and are of even lengths 10,12 and 14, respectively. Hence the quotient space $M_{*}^{5}=\mathbb{H}^{5} / \Gamma_{5}^{*}$ is an orientable cusped hyperbolic 5 -manifold of volume $\frac{13 \zeta(3)}{2}$.

Now let us analyse the fundamental group $\pi_{1}\left(M_{*}^{5}\right) \cong \Gamma_{*}^{5}$ in more detail. Because the group $\Gamma_{5}=[6,3,3,3,3,6]$ is an arithmetic reflection group (defined over $\mathbb{Q}$ ), the group $\pi_{1}\left(M_{*}^{5}\right)$ is an arithmetic lattice. One may check using the Reidemeister-Schreier Rewrite function in MAGMA that the elements of the generating-set $S_{*}:=\{u, v, w\}$ satisfy the set $R_{*}$ of defining relations given in Figure 9, so that $\Gamma_{*}^{5}=\left\langle S_{*} \mid R_{*}\right\rangle$,.

In order to understand the geometry of the generators $u, v, w$ of $\pi_{1}\left(M_{*}^{5}\right)$, we represent the generators $a, b, \ldots, g$ of $[6,3,3,3,3,6]$ by means of positive Lorentz matrices $A, B, \ldots, G \in \mathrm{O}^{+}(5,1)$, as given in Figure 10; see [8, p. 96]. Here, a matrix $M \in \mathrm{O}^{+}(5,1)$ is written as a 6 -tuple $\left[m_{1}, m_{2}, \ldots, m_{6}\right.$ ] of vectors $m_{1}, m_{2}, \ldots, m_{6}$ with respect to the canonical basis $\left\{e_{1}, e_{2}, \ldots, e_{6}\right\}$ of $\mathbb{R}^{6}$.

In this way, the three elements $u, v, w$ can be represented conveniently by matrices $U, V, W$ in $\mathrm{O}^{+}(5,1)$. It turns out that the characteristic polynomial of each of these three matrices has precisely one pair of zeros $\tau, \tau^{-1} \in \mathbb{R}$ with absolute values $\neq 1$, whereas all other zeros lie on the unit circle. The value $\tau>1$ is the exponential of the translation length along the axis of the loxodromic element in question (in the direction of the attractive fixed point). Hence, the elements $u, v, w$ are all loxodromic. Furthermore, one may check that the element $z$ given by

$$
z:=v w^{-1}=(e c d g f g d c e)(f e g f g e f)
$$

is parabolic. As $c$ and $d$ commute with both $f$ and $g$ (see Figure 4), the element $z$ is a product of the form $z=[r, f]=r f r f$ where $r:=e g f g e$ is the reflection with respect to the hyperbolic hyperplane $e_{3}^{\perp} \cap \mathbb{H}^{5}$ given by the Lorentz matrix $\operatorname{diag}(1,1,-1,1,1,1)$.

Next, as mentioned in Section 1, the manifold $M_{*}^{5}$ is closely related to the highly symmetric ideal birectified regular 5-simplex $\mathcal{B}=r_{2} \hat{S}_{\text {reg }}$. The presentation $\left\langle S_{*} \mid R_{*}\right\rangle$, for $\pi_{1}\left(M_{*}^{5}\right)$ given earlier does not help to determine the order of the symmetry group $I\left(M_{*}^{5}\right)$ of $M_{*}^{5}$ or to detect non-trivial subgroups acting fixed-point freely, but nevertheless we can still prove the following theorem, which resulted from following up a helpful suggestion by the referee.

```
\(1=v^{-1} u w^{-1} u^{-2} v w^{-1} u^{2} w u^{-1} v^{2} w v^{-2}\)
    \(=w^{2} u^{-1} v^{2} u^{-1} v u w^{-1} u v^{-1} u v^{-2} u w^{-1} u^{-2}\)
    \(=u w^{-1} u v^{-1} u w v^{-2} u w^{-1} u v^{-2} w u w v^{-2} u w^{-1}\)
    \(=v^{3} w^{-1} u^{-1} v w u^{-1} v^{2} u^{-1} v^{2} u w^{-1} u v^{-2} u^{2} w u^{-1} v\)
    \(=u^{-1} v w u^{-1} v^{2} u w u^{-1} v u w^{-1} u w^{-1} u^{-1} v w^{-1} u^{2} w u^{-1} v^{2}\)
    \(=w^{-1} u w^{-1} u^{-1} v u^{-1} w u^{-1} v^{-1} u w^{-1} u^{-1} w^{-1} u^{-1} w^{-1} v u w^{-1} u v^{-1} w^{-1} u w^{-1}\)
    \(=w^{-1} u w^{-1} u^{-1} w^{-1} u^{-1} v u^{-1} w u^{-1} v^{-1} u w^{-1} u^{-1} w^{-1} u w^{-2} v u w^{-1} u v^{-1}\)
    \(=v u w^{-1} u v^{-1} u w v^{-2} u w^{-1} v^{-1} u v^{-2} u w^{-1} v^{-1} u w v^{-1} u w u^{-1}\)
    \(=u w u^{-1} w u w v^{-2} u w^{-1} v^{-1} w^{2} u^{-1} v^{2} w^{-1} u^{-1} w^{-1} u w^{-1} u^{-1} v w^{-1}\)
    \(=v^{2} w^{-1} u w^{-2} v u w^{-1} u v^{-1} w^{-1} v^{2} u^{-1} w^{-1} v w u^{-1} v^{2} w^{-1} u^{-1} w^{-1}\)
    \(=w v w u^{-1} v^{2} w^{-1} u^{-1} w^{-1} v u w^{-1} u v^{-3} u w^{-1} u^{-1} w v^{-1} u w u^{-1}\)
    \(=w^{-1} u^{-1} w^{-1} v u w u^{-1} w u w v^{-2} u w^{-1} u v w^{-1} u^{-1} v u^{-1} w u^{-1} v^{-1} u\)
    \(=v^{-1} u w^{-1} u^{-1} w^{-1} v u w^{-1} u v^{-1} w^{-1} u w^{-1} u^{-1} w u^{-1} v^{2} w^{-1} u^{-1} w^{-1} u w^{-1} u^{-1} v^{-1}\)
    \(=w u^{-1} w v u^{-1} w u^{-1} v^{-1} w u w v^{-2} u w^{-3} v u w^{-1} u v^{-1} w^{-1} v^{2} u^{-1}\)
    \(=w u^{-1} v u^{-1} w u^{-1} v^{-1} u w^{-1} u^{-2} v w u^{-1} w v u^{-1} w u^{-1} v^{-1} w^{2} v^{-1} u w u^{-1}\)
    \(=w^{-1} u w^{-1} u^{-1} v w^{-1} u w u^{-1} v^{-1} u w^{-1} u^{-2} v^{2} u^{-1} w^{2} u^{-1} w u w v^{-2} u w^{-1} u\)
    \(=u w u^{-1} v u w^{-1} u v^{-1} w u^{-1} v^{2} w^{-1} u^{-1} w^{-1} u w^{-2} u v^{-2} w v u^{-1} w u^{-1} v^{-1} w\)
    \(=u^{-1} w u^{-1} v^{2} w^{-1} u^{-1} w^{-1} u w^{-1} u^{-1} v w^{-1} u^{-1} w^{-1} u w^{-1} u^{-1} v w^{-1} u^{-1} v w u^{-1} v^{2} w^{-1} u^{-1} w^{-1}\)
    \(=v w u^{-1} v^{2} w^{-1} u^{-1} w^{-1} u w^{-1} u^{-2} v w u^{-1} v^{2} u w u^{-1} v u^{2} w u^{-1} v u w^{-1} u v^{-1} u\)
    \(=v^{-2} u^{2} w u^{-1} v^{3} u w u^{-1} w u v^{-2} u w^{-1} u^{-2} w v u w u^{-1} w v u^{-1} w u^{-1} v^{-1} w u\)
    \(=u^{-1} w u^{-1} v^{2} w^{-1} u^{-1} w^{-1} u w^{-1} u^{-1} v w^{-1} u^{-1} w v^{-1} u w u^{-1} w u^{-1} v u^{-1} w u^{-1} v^{2} w^{-1} u^{-1} w^{-1} u^{2} w u^{-1} v^{2}\)
    \(=v^{-1} u w^{-1} u^{-1} w v^{-1} u w u^{-1} w^{2} u w u^{-1} v^{2} w v^{-2} u w^{-1} u^{-1} w v^{-1} u w u^{-1} w v^{-2} u w^{-1} u^{-1} w v^{-2}\).
```

FIGURE 9 Defining relations for the subgroup generated by $S_{*}$

$$
\begin{aligned}
A= & {\left[-e_{1}, e_{2}, e_{3}, e_{4}, e_{5}, e_{6}\right] } \\
B= & {\left[-\frac{1}{2} e_{1}+\frac{\sqrt{3}}{2} e_{2}, \frac{\sqrt{3}}{2} e_{1}+\frac{1}{2} e_{2}, e_{3}, e_{4}, e_{5}, e_{6}\right] } \\
C= & {\left[e_{1},-e_{2}+2 e_{5}+2 e_{6}, e_{3}, e_{4}, 2 e_{2}-e_{5}-2 e_{6},-2 e_{2}+2 e_{5}+3 e_{6}\right] } \\
D= & {\left[e_{1}, e_{2}, \frac{1}{2} e_{3}-\frac{1}{\sqrt{2}} e_{4}-\frac{1}{2} e_{5},-\frac{1}{\sqrt{2}} e_{3}-\frac{1}{\sqrt{2}} e_{5},-\frac{1}{2} e_{3}-\frac{1}{\sqrt{2}} e_{4}+\frac{1}{2} e_{5}, e_{6}\right] } \\
E= & {\left[e_{1}, e_{2}, \frac{1}{2} e_{3}+\frac{\sqrt{3}}{2} e_{4}+\frac{3-\sqrt{6}}{2} e_{5}+\frac{3-\sqrt{6}}{2} e_{6}, \frac{\sqrt{3}}{2} e_{3}-\frac{1}{2} e_{4}+\frac{3(\sqrt{2}-\sqrt{3})}{2} e_{5}+\frac{3(\sqrt{2}-\sqrt{3})}{2} e_{6},\right.} \\
& \frac{3-\sqrt{6}}{2} e_{3}+\frac{\sqrt{3}(-3+\sqrt{6})}{2} e_{4}-\left(\frac{13}{2}-3 \sqrt{6}\right) e_{5}-\left(\frac{15}{2}-3 \sqrt{6}\right) e_{6}, \\
& \left.-\frac{3-\sqrt{6}}{2} e_{3}-\frac{\sqrt{3}(-3+\sqrt{6})}{2} e_{4}+\left(\frac{15}{2}-3 \sqrt{6}\right) e_{5}+\left(\frac{17}{2}-3 \sqrt{6}\right) e_{6}\right] \\
F= & {\left[e_{1}, e_{2},-e_{3}+2 e_{5}+2 e_{6}, e_{4}, 2 e_{3}-e_{5}-2 e_{6},-2 e_{3}+2 e_{5}+3 e_{6}\right] } \\
G= & {\left[e_{1}, e_{2},-\frac{1}{2} e_{3}-\frac{\sqrt{3}}{2} e_{4}+\frac{3+\sqrt{6}}{2} e_{5}+\frac{3+\sqrt{6}}{2} e_{6},-\frac{\sqrt{3}}{2} e_{3}+\frac{1}{2} e_{4}+\frac{\sqrt{2}+\sqrt{3}}{2} e_{5}+\frac{\sqrt{2}+\sqrt{3}}{2} e_{6},\right.} \\
& \frac{3+\sqrt{6}}{2} e_{3}+\frac{\sqrt{2}+\sqrt{3}}{2} e_{4}-\left(\frac{3}{2}+\sqrt{6}\right) e_{5}-\left(\frac{5}{2}+\sqrt{6}\right) e_{6}, \\
& \left.-\frac{3+\sqrt{6}}{2} e_{3}-\frac{\sqrt{2}+\sqrt{3}}{2} e_{4}+\left(\frac{5}{2}+\sqrt{6}\right) e_{5}+\left(\frac{7}{2}+\sqrt{6}\right) e_{6}\right]
\end{aligned}
$$

FIGURE 10 The generators of [6,3,3,3,3,6] as elements in $\mathrm{O}^{+}(5,1)$

Theorem 3. The symmetry group $I\left(M_{*}^{5}\right)$ of $M_{*}^{5}$ is isomorphic to the symmetric group $S_{4}$, of order 24, and contains no non-trivial subgroup that acts without fixed points on $M_{*}^{5}$.

Proof. First, we note that by a theorem of Mühlherr [17, Theorem 3.3], the automorphism group of the Coxeter group $\Gamma_{5}=[6,3,3,3,3,6]$ is the semi-direct product of $\Gamma_{5}$ by the cyclic group $C_{2}$ induced by the automorphism taking ( $a, b, c, d, e, f, g$ ) to ( $g, f, e, d, c, b, a$ ), corresponding to the non-trivial symmetry of its Coxeter diagram.

It follows that the normaliser of $\Gamma_{5}$ in Isom $\mathbb{H}^{5}$ is isomorphic to this semi-direct product, and that makes it easy for us to find $I\left(M_{*}^{5}\right) \cong N\left(\Gamma_{*}^{5}\right) / \Gamma_{*}^{5}$. In particular, our subgroup $\Gamma_{*}^{5}$ has index 5760 in $N\left(\Gamma_{5}\right)$, and a MAGMA computation shows that the normaliser $N\left(\Gamma_{*}^{5}\right)$ of $\Gamma_{*}^{5}$ in $N\left(\Gamma_{5}\right)$ has index 240 in $N\left(\Gamma_{5}\right)$, and that $N\left(\Gamma_{*}^{5}\right) / \Gamma_{*}^{5}$ is isomorphic to $S_{4}$, of order $24=5760 / 240$.

To complete the proof, we show that the only torsion-free subgroup of $N\left(\Gamma_{*}^{5}\right)$ containing $\Gamma_{*}^{5}$ is $\Gamma_{*}^{5}$ itself.

For suppose there is a larger one, say $H$. Then as $\Gamma_{*}^{5}$ has index 24 in $N\left(\Gamma_{*}^{5}\right)$ and index 5760 in $N\left(\Gamma_{5}\right)$, we see that $H$ has index at most 2880 in $N\left(\Gamma_{5}\right)$. But also $K:=H \cap \Gamma_{5}$ is a torsion-free subgroup of $\Gamma_{5}$, so $K$ has index at least 2880 in $\Gamma_{5}$ and hence index at least 5760 in $N\left(\Gamma_{5}\right)$. It follows that $K$ has index 2 in $H$ and index 2880 in $N\left(\Gamma_{5}\right)$, and so $K=H \cap \Gamma_{5}=\Gamma_{*}^{5}$.

In particular, $H$ contains $\Gamma_{*}^{5}$ as a subgroup of index 2 and so $H / \Gamma_{*}^{5}$ is in one of the three conjugacy classes of subgroups of order 2 in $N\left(\Gamma_{*}^{5}\right) / \Gamma_{*}^{5} \cong S_{4}$. A further MAGMA computation shows that up to conjugacy, $H$ is generated by $\Gamma_{*}^{5}$ and one of the three elements:

$$
z_{1}:=a b g f g f a b a b e f g c d b c b, \quad z_{2}:=a b g f g f g f b a \quad \text { and } \quad z_{3}:=a b g f g f a b a b g f t .
$$

On the other hand, $H$ is not a subgroup of $\Gamma_{5}$, so it must contain an element lying outside $\Gamma_{5}$, and therefore $H$ cannot be generated by $\Gamma_{*}^{5}$ and one of $z_{1}$ or $z_{2}$. But also the element $z_{3}$ has order 2 , as

$$
(a b g f g f a b a b g f t)^{2}=a b g f g f a b a b g f g f a b a b g f g f g a b=(a b)^{6}(f g)^{6}=1,
$$

and this is impossible because $H$ is torsion-free. Thus no such subgroup $H$ exists.
The ideal birectified regular 5-simplex $\mathcal{B}$ can be dissected into 720 copies of the Coxeter pyramid with Coxeter symbol [6,3,3,3,3,6]. Its associated reflection group $\Gamma_{5}$ contains the Coxeter pyramid group $\Lambda_{5}$ as a subgroup of index 4; see Section 2. The Coxeter diagram of $\Lambda_{5}$ depicted in Figure 11 is distinguished by having edges only of weight 3 , and arising as a mutation of the quiver indexed by the Weyl group $A_{7}$. More concretely, in [6], Felikson and Tumarkin used techniques of quiver mutations from the theory of cluster algebras in order to construct manifolds whose symmetry groups contain a given finite Weyl group. In this way, they are able to determine all finite-volume hyperbolic manifolds arising from quivers of finite type whose nodes are connected by at most one arrow (or quivers of finite type given by simply-laced graphs). In fact, the fundamental groups of their manifolds are torsion-free subgroups of certain finite-covolume hyperbolic Coxeter groups whose Coxeter diagrams have weights only 2 and 3 . In particular, the corresponding Coxeter polyhedra have mutually intersecting facets forming dihedral angles equal to either $\frac{\pi}{2}$ or $\frac{\pi}{3}$; this family of polyhedra has been classified by Prokhorov [18]. The single relevant example distinct from simplices in $\mathbb{H}^{5}$ is the Coxeter polyhedron associated with $\Lambda_{5}$.

The corresponding manifold $Q^{5}$ found by Felikson and Tumarkin arises as follows. Consider the natural set $S=\left\{s_{1}, \ldots, s_{7}\right\}$ of reflections generating the group $\Lambda_{5}$ as indexed in Figure 11. These


FIGURE 11 The generators of the group $\Lambda_{5}$
satisfy a set of relations that can be read off from the Coxeter diagram of $\Lambda_{5}$. Following [6, Section 3, (R3)], construct the two cycle relators,

$$
r_{1}:=\left(s_{3} s_{1} s_{2} s_{1}\right)^{2}=(c b a b a b)^{2} \quad \text { and } \quad r_{2}:=\left(s_{5} s_{6} s_{7} s_{6}\right)^{2}=(\text { ef } g f g f)^{2},
$$

and consider the normal closure $N_{C}$ of $\left\{r_{1}, r_{2}\right\}$ in $\Lambda_{5}$. By the Manifold Property [6, Theorem 6.2], the group $N_{C}$ is a torsion-free subgroup of index 40320 in $\Lambda_{5}$ with quotient manifold $Q^{5}=\mathbb{H}^{5} / N_{C}$.

Moreover, it can be shown that $Q^{5}$ has 70 cusps and symmetry group $I\left(Q^{5}\right)$ containing the Weyl group $A_{7}$ of order 8!; see [6, Section 5.3, Table 5.1]. As for its volume, the observation (2.4) allows us to deduce that

$$
\operatorname{vol}_{5}\left(Q^{5}\right)=4 \cdot 8!\cdot \operatorname{vol}_{5}([6,3,3,3,3,6])=364 \zeta(3) \approx 437.54871
$$

In fact the Felikson-Tumarkin manifold $Q^{5}$ is a cover of our manifold $M_{*}^{5}$, because the torsionfree subgroup $N_{C}$ of index 40320 in $\Lambda_{5}$ is contained in the torsion-free subgroup of index 2880 we found in proving Theorem 2. This is easily verifiable using MAGMA.

## 5 | SOME FURTHER OBSERVATIONS

We finish this paper by exploiting the conclusions of Theorem 1 about small index torsion-free subgroups for the related cases of the hyperbolic Coxeter groups $[\infty, 3,3,3,6],[3,3,6]$ and $[\infty, 3,6, \infty]$.

Theorem 4. The smallest index of a torsion-free subgroup in the Coxeter group $[\infty, 3,3,3,6]$ is 720, achieved for example by the torsion-free subgroup generated by def, acdcbfeab, $a b c d e f e d f e f d e f e f d c b, \quad b c d e d f e d f e f d e f e f c d c b$ and $b c d e f e d c b a b c d e f e d c a b$, where $a, b, c, d, e$ and $f$ are the canonical generators for the Coxeter group. This subgroup gives rise to a non-orientable hyperbolic 4-manifold of smallest volume $\frac{4 \pi^{2}}{3}$, with four cusps and with first homology group $\mathbb{Z} \oplus \mathbb{Z}_{2}^{4}$.

Proof. First, the Euler characteristic of the Coxeter group $\Gamma_{4}=[\infty, 3,3,3,6]$ is $1 / 720$, so the minimum index of a torsion-free subgroup is at least 720 . On the other hand, a MAGMA computation shows that the subgroup given in the statement of the theorem has index 720, contains no conjugate of any of the representative torsion elements $a, b, c, d, e, f, a c, a d, a e, a f, b c, b d, b e, b f, c d$, $c e, c f, d e, d f, a c e, a c f, a d f, b d f,(e f)^{2},(e f)^{3}, a(e f)^{3}, a c(e f)^{3}, b c d e, b c(e f)^{2}, b(e f)^{3}$ and $c(e f)^{3}$ and has abelianisation $\mathbb{Z} \oplus \mathbb{Z}_{2}^{4}$.

The associated hyperbolic 4-manifold is non-orientable, and it has four cusps. Indeed the Coxeter polyhedron related to $\Gamma_{4}$ has precisely one ideal vertex $v_{0}$, with stabiliser subgroup $\Gamma_{4}\left(v_{0}\right)$ isomorphic to $\langle a, b\rangle \times\langle d, e, f\rangle$. The cusps of the manifold are in one-to-one correspondence with the orbits of the group $\Gamma_{4}\left(v_{0}\right)$ in the action of $\Gamma_{4}$ on the cosets of the torsion-free subgroup, and
a MAGMA computation shows that there are exactly four such orbits, of lengths 48, 96, 144 and 432.

In the case of the Coxeter group [3,3,6], and by means of a simple MAGMA computation, we rediscover the following well-known fact mentioned in Section 1.

Theorem 5. The smallest index of a torsion-free subgroup in the Coxeter group [3,3,6] is 24, achieved by the torsion-free subgroup generated by $u=a b c d c$ and $v=b c d$, which satisfy $u^{2} v^{2}=v u$, where $a, b, c$ and $d$ are the canonical generators for the Coxeter group. This subgroup is unique up to conjugation and yields the fundamental group of Gieseking's 1-cusped non-orientable hyperbolic 3manifold $G$ of volume $v_{3}$, with infinite cyclic first homology group $\mathbb{Z}$.

Associated with the Euclidean Coxeter group [6,3] is the hyperbolic Coxeter pyramid group $[\infty, 6,3, \infty] \subset$ Isom $\Vdash^{3}$ of covolume $\frac{5}{4} \pi\left(\frac{\pi}{3}\right)$. Part of our Theorem 1 can be extended as follows.

Theorem 6. The smallest index of a torsion-free subgroup in the Coxeter group $[\infty, 6,3, \infty]$ is 24 , achieved for example by the orientation-preserving torsion-free subgroup generated by $a b, a c d c b c$, and acebcd,, and also by the torsion-free subgroup generated by ab, acbcd, and acdcebc, (which does not preserve orientation), where $a, b, c, d$ and $e$ are the canonical generators for the Coxeter group. These subgroups give rise to one orientable and one non-orientable hyperbolic 3-manifold, each with three cusps and volume $30 \mathrm{~J}\left(\frac{\pi}{3}\right) \approx 10.14941$, and each with first homology group $\mathbb{Z}^{3}$.

Proof. First, note that the subgroup generated by $b, c$ and $e$ is finite and isomorphic to $D_{6} \times C_{2}$, of order 24 , and so the minimum index of a torsion-free subgroup is at least 24 . On the other hand, MAGMA computations show that each of the two subgroups given in the statement of the theorem has index 24 and contains no conjugate of any of the representative torsion elements $a, b, c, d, e$, $a c, a d, a e, b c, b d, b e, c d, c e, a c d$ and $b c e$ and has abelianisation $\mathbb{Z}^{3}$.

Each of the two associated hyperbolic 3-manifolds has three cusps. Indeed, the Coxeter polyhedron related to the group $\left[\infty, 6,3, \infty\right.$ ] has two ideal vertices $v_{1}$ and $v_{2}$, with stabiliser subgroups isomorphic to $H_{1}=\langle b, c, d\rangle \cong[6,3]$ and $H_{2}=\langle a, b\rangle \times\langle d, e\rangle$, respectively. Finally, a MAGMA computation determines the number of orbits of the stabilisers in the action of $[\infty, 6,3, \infty]$ on the cosets of each of two torsion-free subgroups of index 24 in $[\infty, 6,3, \infty]$. In the case of $H_{1}$, there is a single orbit of length 24 , whereas in the case of $H_{2}$, there are two orbits of lengths 8 and 16 . Hence, there are three cusps in total for each of the two torsion-free subgroups.

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